**Multi-Axis Stages** 

Motorized Mirror Mounts

**Rotation Stages** 

**Drive Electronics** 

& Auto-Alignment

Actuators & Adjusters

**Brief Tutorials** 



## Benchtop apt™ Stepper Motor Controllers...Page 2 of 2

### **Specifications**

- Input/Output:
  - Motor Drive Channel (15-Pin D-Type Female)
    - 2-Phase Bipolar Motor Drive Output
    - Differential Quadrature Encoder Interface
    - Forward, Reverse Limit Switch Inputs
  - Motor Control (15-Pin D-Type Female)
    - Jog Forward/Back
    - Enable/Disable Interlock
    - User Logic Outputs/Inputs
    - Single-Ended Analog Input (0-10V)
    - Trigger In/Out

- Compatible Motors
  - Peak Powers: 5-50W
  - Average Power: 25W Maximum
  - Step Angle Range: 20°-1.8°
  - Coil Resistance (Nominal):  $4-15\Omega$
  - Coil Inductance (Nominal): 4-15mH
  - Rated Phase Currents (Nominal): 100mA-1A
- Resolution
  - 128 Microsteps per Full Step
  - 200 Step Motor 25,600 Microsteps per Revolution
- **■** Motor Power: Up to 48V/50W (Peak)
- **Input Power Requirements** 
  - **Voltage:** 85-264VAC
  - Power: 200W (100W BSC101)

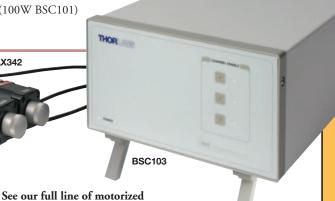
MAX342

• Fuse: 3.15A

Stage sold

separately

- Motor Speeds: Up to 600 RPM (for 200 Full Step Motor)
- **Encoder Feedback Bandwidth:** 500,000 Counts per Seconds
- Housing Dimensions (W x D x H):
  - BSC101
    - 152 x 244 x 104mm (6" x 9.6" x 4.1")
  - BSC102, BSC103 240 x 360 x 133mm (9.5" x 14.2" x 5.2")
- Instrument Weight:
  - BSC101 3.18kg (7lbs)
  - BSC102, BSC103 6.7kg (14.75lbs)

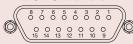


# **MOTOR CHANNEL**



Pin	Description	Pin	Description
1	5 V User	9	0 V User
2	Jog Fwd	10	Jog Back
3	Not Used	11	Analog In
4	Trig In	12	Trig Out
5	EN Return	13	Enable
6	RS-232TX	14	RS-232 RX
7	User In	15	User Out (o/c)
8	Keyed Pin		

#### **MOTOR DRIVE**



Pin	Description	Pin	Description				
1	Encoder A +ve	9	CW Limit Stwitch				
2	Encoder A -ve	10	CCW Limit Switch				
3	Encoder B +ve	11	0 V User				
4	Encoder B -ve	12	Not Used				
5	5 V User	13	Not Used				
6	Not Used	14	Phase B +				
7	Phase B -	15	Phase A +				
8	Phase A -						

**Full Support for Encoder Feedback** 

The apt<sup>TM</sup> stepper unit also supports encoder feedback through dedicated quadrature encoded pulse (QEP) inputs, one for each channel of operation. A built-in algorithm can be enabled to allow the stepper system to reach and maintain an encoded position through an iterative move sequence. Please see page 271 for details on our linearencoded LNR stage and apt<sup>TM</sup> stepper drive package.

flexure stages starting on page 288.

#### Software Developers Support CD

A developers' kit ships with all of our apt  $^{TM}$  series controllers. This additional software is intended for use by software developers working on large system integration projects which incorporate apt<sup>TM</sup> products. The kit contains an extensive selection of useful code samples as well as tutorial information.

See pages 380-382 for more information on the apt<sup>TM</sup> software included with the BSC Series Controllers.

ITEM#	\$	£	€	RMB	DESCRIPTION
BSC101	\$ 1,351.50	£ 851.40	€ 1.256,90	¥ 12,906.80	Single-Channel Stepper Motor Controller
BSC102	\$ 2,203.20	£ 1,388.00	€ 2.049,00	¥ 21,040.60	Two-Channel apt™ Stepper Motor Controller
BSC103	\$ 2,807.60	£ 1,768.80	€ 2.611,10	¥ 26,812.60	Three-Channel apt <sup>TM</sup> Stepper Motor Controller

